int k=8;

int y=10;

int m=9;

int anahtar=A0;

float okunan\_deger;

float deger;

void setup()

{

pinMode(anahtar, INPUT);

Serial.begin(9600);

}

void loop()

{

okunan\_deger=analogRead(anahtar);

deger=(okunan\_deger\*5)/1024;

Serial.println(deger);

if (deger>4)

{digitalWrite(k,HIGH);}

else

{digitalWrite(k,LOW);

delay(100);}

if (deger<4)

{digitalWrite(y,HIGH);

delay(100);}

else

{digitalWrite(y,LOW);}

}